

# Introduction

Graph clustering is an important problem in many domains. At a high level, given a graph, we want to find sets of related vertices in the graph. This objective can be captured in several ways, so several formulations of the clustering problem exist (such as k-medians). However, until recently, most formulations of clustering did not allow clusters to overlap. Overlapping clusters are of interest in community detection, which motivates the following definition of an  $(\alpha, \beta)$ -cluster [1] in a graph.

Given a graph G = (V, E) (where each vertex has a self-loop), an  $(\alpha, \beta)$ -cluster is a set  $S \subseteq V$  that is internally dense and externally sparse, i.e.

For all  $u \in S$ , u has at least  $\alpha |S|$  neighbors in S

For all  $\nu \notin S$ ,  $\nu$  has at most  $\beta |S|$  neighbors in S



Figure 1: A random graph with overlapping communities

# Hardness Results for Community Detection

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## **Previous work**

Mishra et al [1] introduced this notion and gave an algorithm that finds all  $(\alpha, \beta)$ -clusters with an additional constraint (the 'ρ-champion constraint') in polynomial time. Balcan et al [2] showed instances where the graph has quasi-polynomially many  $(\alpha, \beta)$ -clusters, showed that finding even one cluster is as hard as the hidden clique problem, and gave a quasipolynomial time algorithm to find all such clusters (through a related, but different notion of  $(\Theta, \alpha, \beta)$ -self-determined communities).

# Key Result

It is natural to relax the external sparsity condition and analyze the problem. We formulate the problem as follows : given a graph G and a number k, does G have a  $\frac{3}{4}$ -cluster of size k? We show that this makes the problem NP-hard. We reduce the balanced biclique problem to this problem. The balanced biclique problem is formulated as follows : given a bipartite graph and a size parameter j, is there a copy of  $K_{j,j}$  in the graph?

The reduction is as follows : Given a bipartite graph H and a size parameter j, we simply add a clique of size 2j - 1 to H and fully connect all original vertices in H to the clique. This transformation has the property that the new graph has a  $\frac{3}{4}$ -cluster of size 4j – 1 iff H had a balanced biclique of size 2j.

This reduction generalizes to fractions of the form  $\frac{p+1}{p+2}$ : we simply add a clique of size pj - 1, and make the new size parameter (p+2)j-1.

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# **Future directions**

One immediate hope is to generalize this reduction to any fixed fraction (as opposed to fractions of a specific form). Another possible direction (suggested by Prof Venkat Guruswami) is to approximate (or prove hardness thereof) the density fraction : for example, given a graph G and a size parameter k, is there an induced subgraph of size k with min-degree  $\frac{3}{4}$ , or do all such subgraphs of size k have min-degree at most  $\frac{3}{4} - \epsilon$ ? Another direction that we explored was the following : Balcan et al's algorithm finds  $(\alpha, \beta)$ -clusters when  $\alpha$  and  $\beta$  are constants and node degrees are proportional to cluster sizes. This can only find dense clusters, and they also show that sparser clusters may be super-polynomial in number. Can we find sparse clusters in polynomial time if we assume that the observed edges are randomly sampled from a denser latent graph?

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### References

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